

Average-Energy Games

Patricia Bouyer¹ Kim G. Larsen² Simon Laursen²
Nicolas Markey¹ Mickael Randour¹

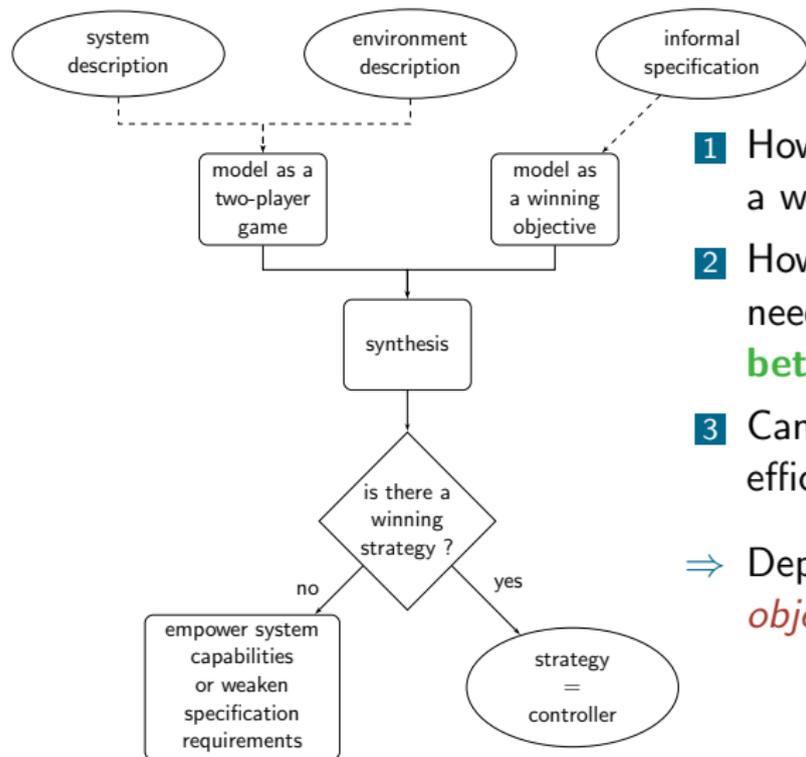
¹LSV - CNRS & ENS Cachan

²Aalborg University

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General context: strategy synthesis in quantitative games



- 1 How complex is it to **decide** if a winning strategy exists?
 - 2 How complex such a **strategy** needs to be? **Simpler is better.**
 - 3 Can we **synthesize** one efficiently?
- ⇒ Depends on the **winning objective.**

The talk in one slide

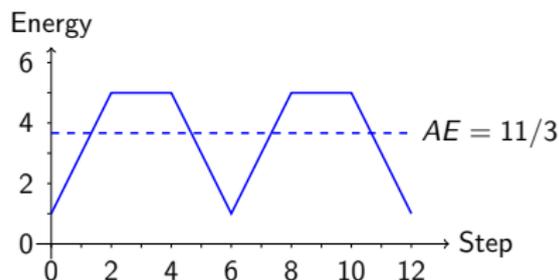
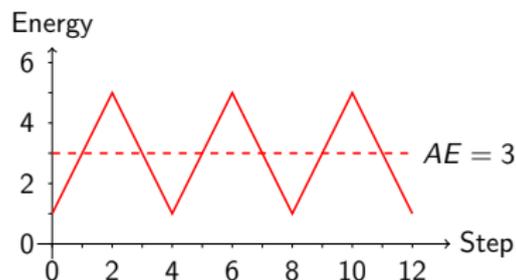
- **“New” quantitative objective**

- ▷ **Total-payoff (TP)** “refines” **mean-payoff (MP)** (MP value = 0)
- ▷ **Average-energy (AE)** “refines” TP

The talk in one slide

■ “New” quantitative objective

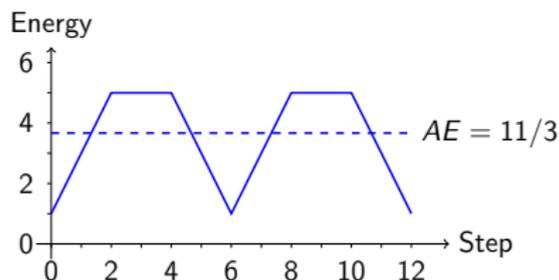
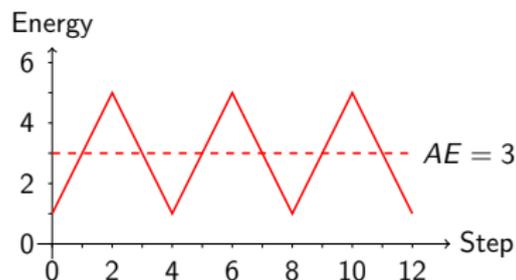
- ▷ Total-payoff (TP) “refines” mean-payoff (MP) (MP value = 0)
- ▷ Average-energy (AE) “refines” TP
- ↪ characterizes the **average energy level** along an infinite play



The talk in one slide

■ “New” quantitative objective

- ▷ Total-payoff (TP) “refines” mean-payoff (MP) (MP value = 0)
- ▷ Average-energy (AE) “refines” TP
- ↪ characterizes the **average energy level** along an infinite play

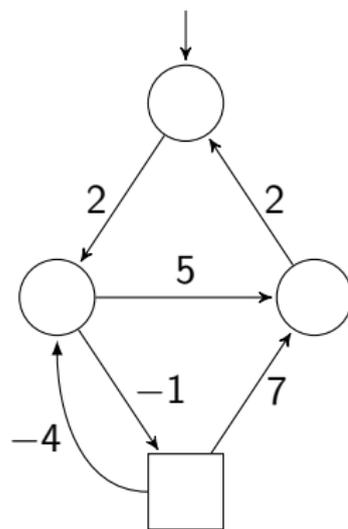


- Conjunction with **energy constraints**: lower and/or upper bounds on the energy level (e.g., fuel tank)

- 1 Context & Definitions
- 2 Average-Energy Games
- 3 Average-Energy with Energy Constraints
- 4 Conclusion

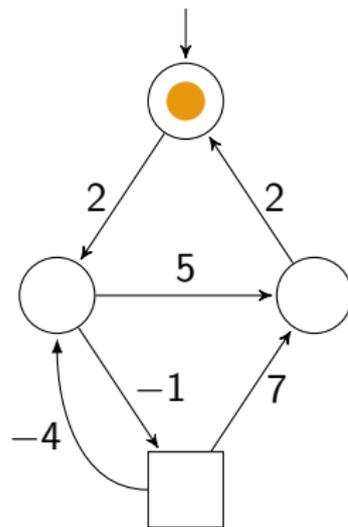
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Two-player turn-based games on graphs



- $G = (S_1, S_2, T, w)$
- $S = S_1 \cup S_2, S_1 \cap S_2 = \emptyset, T \subseteq S \times S, w: T \rightarrow \mathbb{Z}$
- \mathcal{P}_1 states = \bigcirc
- \mathcal{P}_2 states = \square
- Plays have values
 - ▷ $f: \text{Plays}(G) \rightarrow \mathbb{R} \cup \{-\infty, \infty\}$
- Players follow **pure** strategies
 - ▷ $\sigma_i: \text{Prefs}_i(G) \rightarrow S$

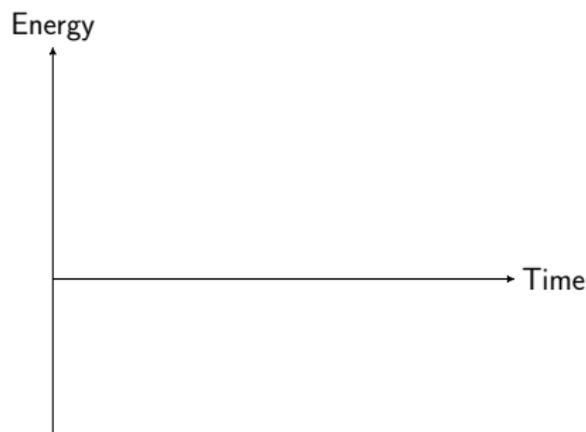
Energy, total-payoff, mean-payoff



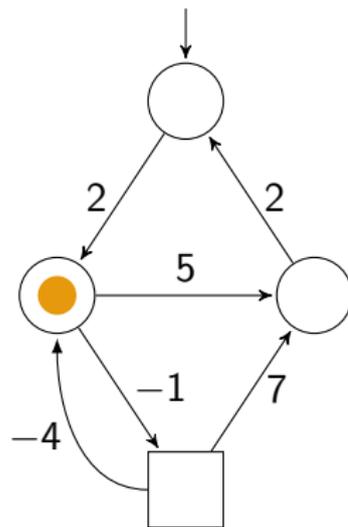
$$\blacksquare EL(\pi(n)) = \sum_{i=0}^{n-1} w(s_i, s_{i+1})$$

$$\blacksquare \overline{TP}(\pi) = \limsup_{n \rightarrow \infty} EL(\pi(n))$$

$$\blacksquare \overline{MP}(\pi) = \limsup_{n \rightarrow \infty} \frac{1}{n} EL(\pi(n))$$



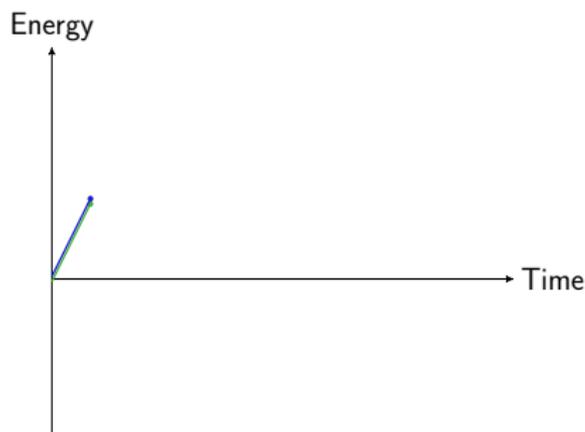
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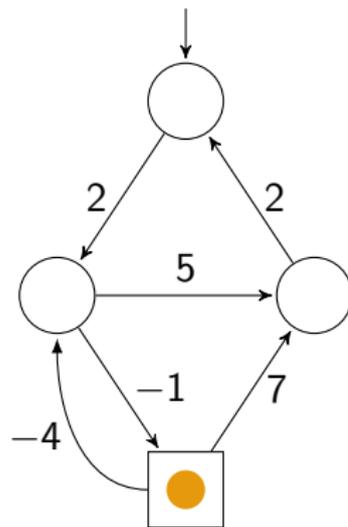
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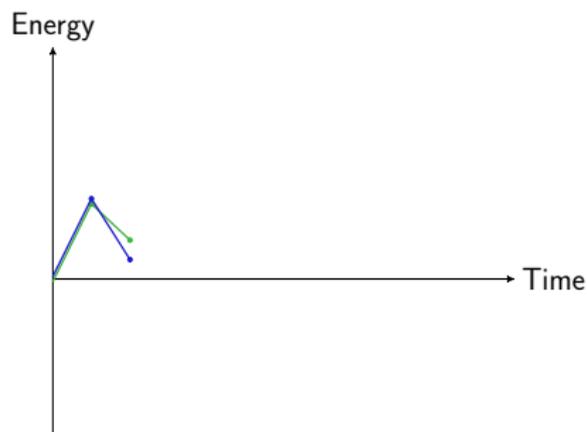
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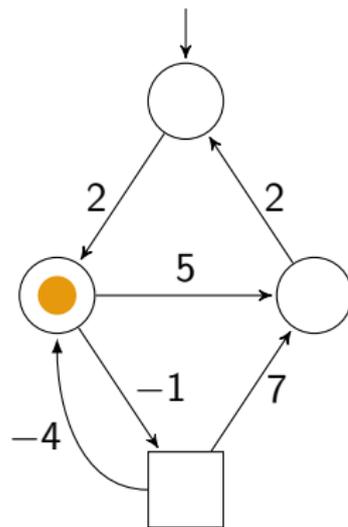
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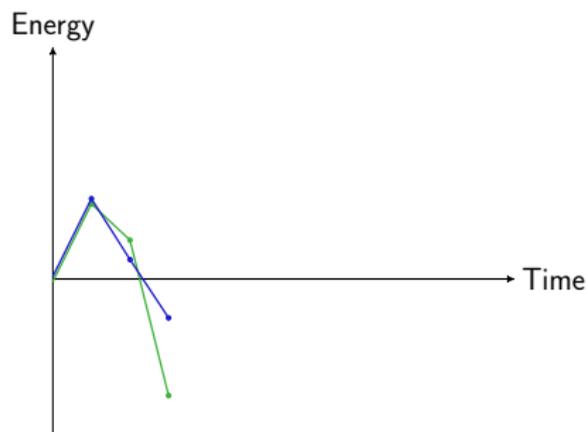
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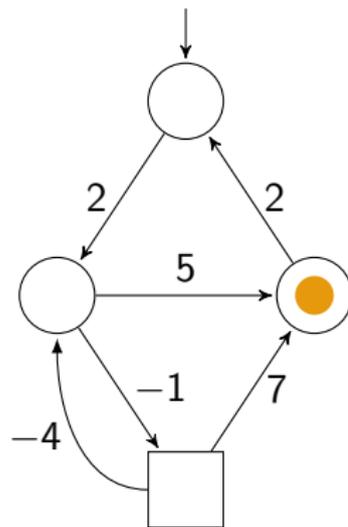
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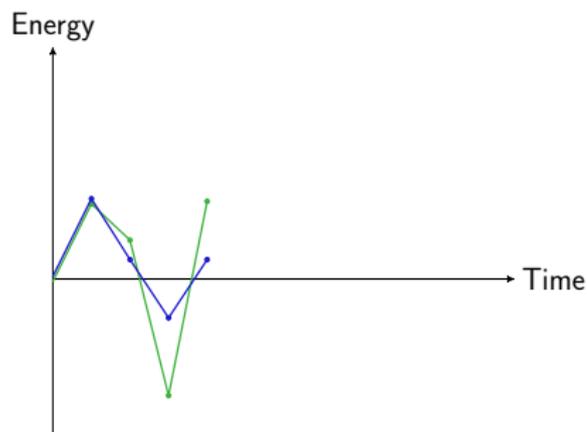
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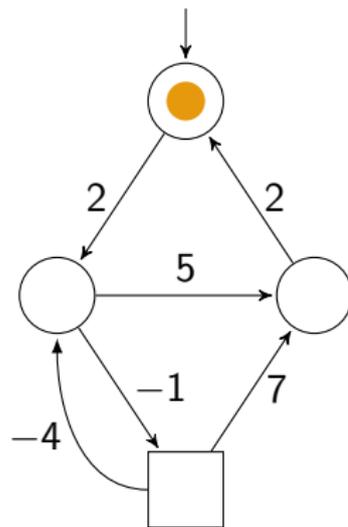
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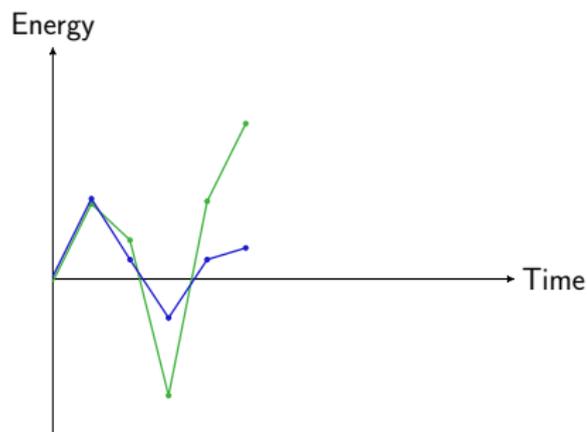
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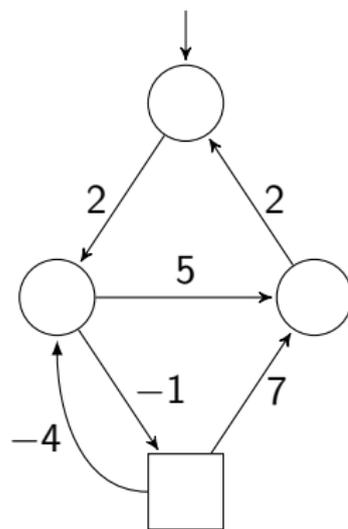
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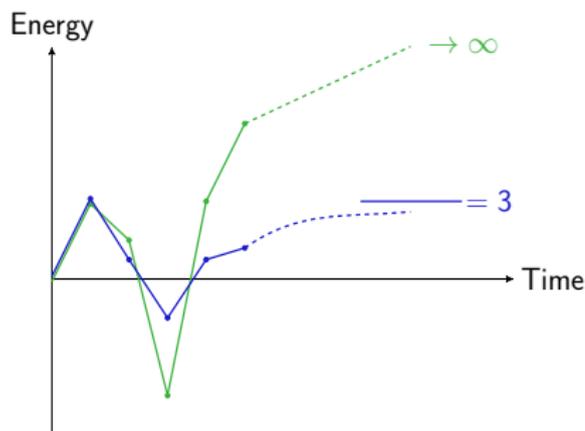


Then, $(2, 5, 2)^\omega$

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Decision problems

■ TP (MP) threshold problem

▷ Given $t \in \mathbb{Q}$ and $s_{\text{init}} \in \mathcal{S}$, $\exists? \sigma_1 \in \Sigma_1$ s.t. $\forall \sigma_2 \in \Sigma_2$,
 $\overline{TP}(\text{Outcome}(s_{\text{init}}, \sigma_1, \sigma_2)) \leq t$

↪ we take the **minimizer** point of view

■ Lower-bounded energy problem

▷ Given $c_{\text{init}} \in \mathbb{N}$ and $s_{\text{init}} \in \mathcal{S}$, $\exists? \sigma_1 \in \Sigma_1$ s.t. $\forall \sigma_2 \in \Sigma_2$,
 $\forall n \geq 0$, $c_{\text{init}} + EL(\text{Outcome}(s_{\text{init}}, \sigma_1, \sigma_2))(n) \geq 0$

↪ **fixed** initial credit

■ Lower- and upper-bounded energy problem

▷ Given $c_{\text{init}} \in \mathbb{N}$, $U \in \mathbb{N}$ and $s_{\text{init}} \in \mathcal{S}$, $\exists? \sigma_1 \in \Sigma_1$ s.t. $\forall \sigma_2 \in \Sigma_2$,
 $\forall n \geq 0$, $c_{\text{init}} + EL(\text{Outcome}(s_{\text{init}}, \sigma_1, \sigma_2))(n) \in [0, U]$

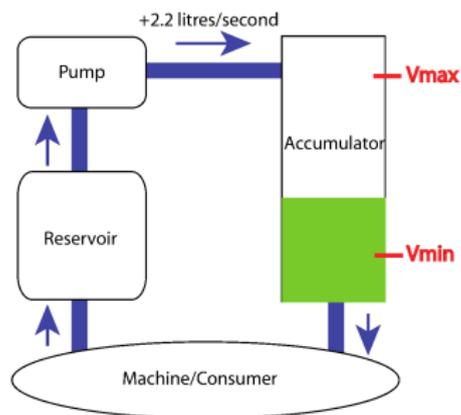
Known results

| Objective | 1-player | 2-player | memory |
|-----------|-------------------------|---|----------------------|
| MP | P [Kar78] | $NP \cap coNP$ [ZP96] | memoryless [EM79] |
| TP | P [FV97] | $NP \cap coNP$ [GS09] | memoryless [GZ04] |
| EG_L | P [BFL ⁺ 08] | $NP \cap coNP$ [CdAHS03, BFL ⁺ 08] | memoryless [CdAHS03] |
| EG_{LU} | PSPACE-c. [FJ13] | EXPTIME-c. [BFL ⁺ 08] | exponential |

- ▶ For all objectives but EG_{LU} , *memoryless* strategies suffice for both players.

Average-energy: motivating example

HYDAC oil pump industrial case study [CJL⁺09] (Quasimodo research project).



Goals:

- 1 Keep the oil level in the safe zone.
 $\hookrightarrow EG_{LU}$
- 2 Minimize the average oil level.
 $\hookrightarrow AE$

\Rightarrow **Conjunction:** AE_{LU}

Related work

- AE appeared in [TV87] as an alternative *total reward* definition.
 - ↪ Not studied until recently.
- Chatterjee and Prabhu use a variant in [CP13].
 - ↪ *Average debit-sum level* objective.
 - ↪ Pseudo-polynomial algorithm.
 - ↪ Complexity and memory requirements are open.
- AE studied independently by Boros et al. in [BEGM15].
 - ↪ Stochastic context.
 - ↪ Similar results but different approach.
- Nothing is known for AE_{LU} .

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Average-energy: definition

Recall

- $EL(\pi(n)) = \sum_{i=0}^{n-1} w(s_i, s_{i+1})$
- $\overline{TP}(\pi) = \limsup_{n \rightarrow \infty} EL(\pi(n))$
- $\overline{MP}(\pi) = \limsup_{n \rightarrow \infty} \frac{1}{n} EL(\pi(n))$

+ infimum variants
TP, MP, AE

Average-energy (AE)

Describes the **average energy level** along a play:

$$\overline{AE}(\pi) = \limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n EL(\pi(i))$$

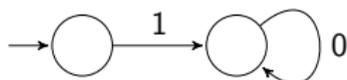
TP “refines” MP

- If \mathcal{P}_1 (minimizer) can ensure $\underline{MP} = \overline{MP} < 0$ (memoryless), he can ensure $\underline{TP} = \overline{TP} = -\infty$.
- If \mathcal{P}_2 (maximizer) can ensure $\underline{MP} = \overline{MP} > 0$ (memoryless), he can ensure $\underline{TP} = \overline{TP} = \infty$.

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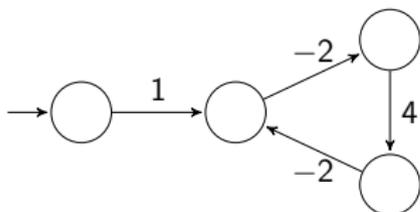
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⇒ **TP discriminates “MP-zero” strategies** depending on the high points (\overline{TP}) or low points (\underline{TP}) of cycles.



$$\overline{MP} = \underline{MP} = 0$$

$$\overline{TP} = \underline{TP} = 1$$



$$\overline{MP} = \underline{MP} = 0$$

$$\overline{TP} = 3, \underline{TP} = -1$$

AE “refines” TP

AE describes the **long-run average EL**

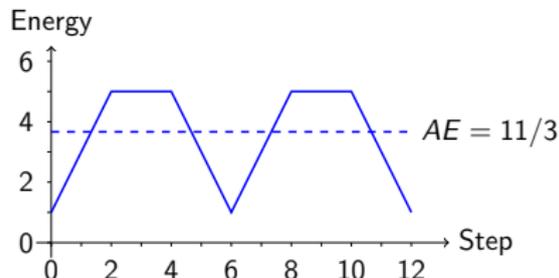
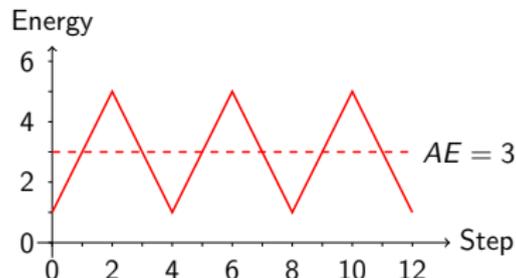
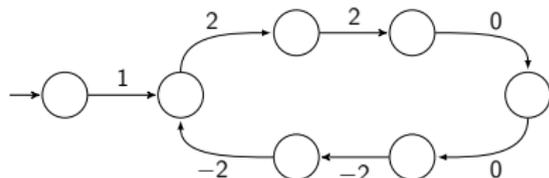
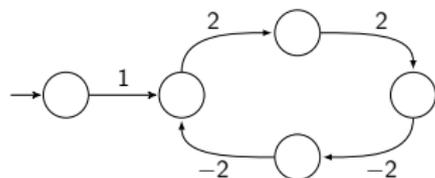
↪ By definition, $\underline{AE}(\pi), \overline{AE}(\pi) \in [\underline{TP}(\pi), \overline{TP}(\pi)]$.

AE “refines” TP

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⇒ **AE discriminates strategies with identical high/low points.**



Identical MP and TP, but AE lower in the first one.

Memoryless determinacy (1/2)

Classical criteria from the literature **cannot be applied out-of-the-box** [EM79, BSV04, AR14, GZ04, Kop06].

- ↪ Common approach: connect *first cycle* games and infinite-duration ones.
- ↪ Requires e.g., closure under *cyclic permutation* and *concatenation* [AR14].

Intuitively: ability to **mix and shuffle** good cycles and stay good.

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Not true in general for AE!

$$\mathcal{C}_1 = \{-1\}, \mathcal{C}_2 = \{1\}, \mathcal{C}_3 = \{1, -2\}$$

$$AE(\mathcal{C}_1\mathcal{C}_2) = (-1 + 0)/2 = -1/2 < AE(\mathcal{C}_2\mathcal{C}_1) = (1 - 0)/2 = 1/2$$

$$AE(\mathcal{C}_3) = 0 \text{ but } AE(\mathcal{C}_3\mathcal{C}_3) = -1/2 < 0$$

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Intuitively: ability to **mix and shuffle** good cycles and stay good.

We can only shuffle/repeat cycles that are neutral w.r.t. the energy level!

↔ **zero-cycles**

Memoryless determinacy (2/2)

Two key properties:

1 Extraction of **prefixes**

▷ Let $\rho \in \text{Prefs}(G)$, $\pi \in \text{Plays}(G)$. Then,

$$\overline{AE}(\rho \cdot \pi) = EL(\rho) + \overline{AE}(\pi).$$

2 Extraction of a **best cycle**

▷ Given an infinite sequence of *zero-cycles*, one can select and repeat a *best cycle* to minimize the average-energy.

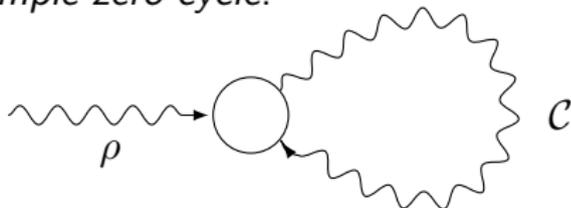
One-player games: strategy

Sketch (minimizer)

- 1 If you can ensure $MP < 0$, do it.
 - ▷ Memoryless [EM79], implies $AE = -\infty$.
- 2 If you *cannot* ensure $MP = 0$, forget it.
 - ▷ You are doomed, $AE = \infty$.
- 3 Play the strategy that minimizes

$$\overline{AE}(\rho \cdot \mathcal{C}^\omega) = EL(\rho) + \overline{AE}(\mathcal{C}),$$

where \mathcal{C} is a *simple zero-cycle*.



↔ Picking the best combination can be done **without memory**.

One-player games: P algorithm (1/2)

- Case $MP < 0$ is easy
 - ▶ Look for a negative cycle (e.g., Bellman-Ford, $\mathcal{O}(|S|^3)$)

One-player games: P algorithm (1/2)

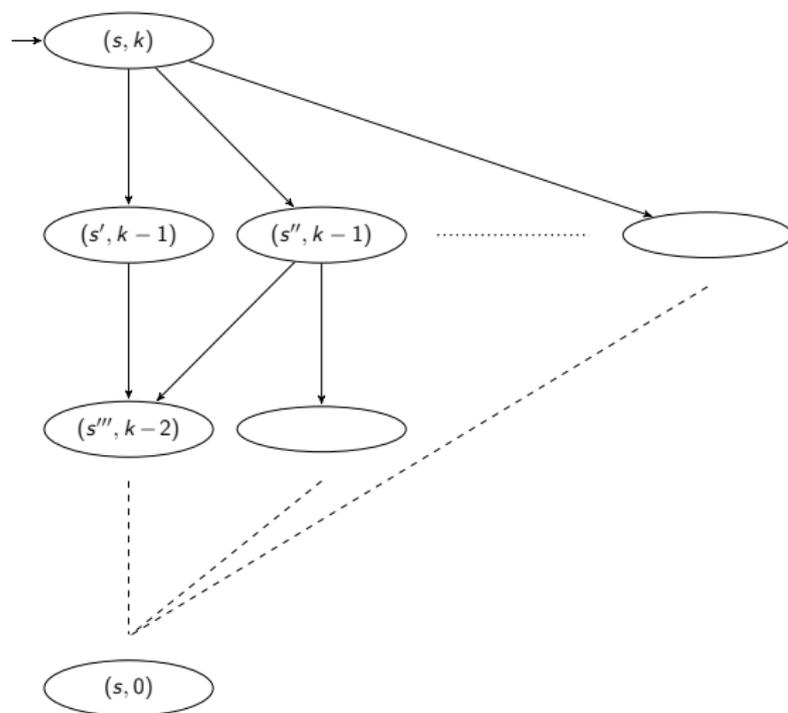
- Case $MP < 0$ is easy
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- Assume $MP = 0$: **pick the best combination** of ρ and \mathcal{C}
 - ▷ Computing the best ρ for each state is easy with classical graph algorithms (e.g., Bellman-Ford).
 - ▷ **Main task**: computing the best \mathcal{C} (AE-wise) for each state.

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 - ▷ **Main task**: computing the best \mathcal{C} (AE-wise) for each state.
- For each state, we compute the best cycle of length k , for all $k \in \{1, \dots, |S|\}$, then pick the best one.
 - ▷ Need to compute $\mathcal{C}_{s,k}$ in polynomial time.

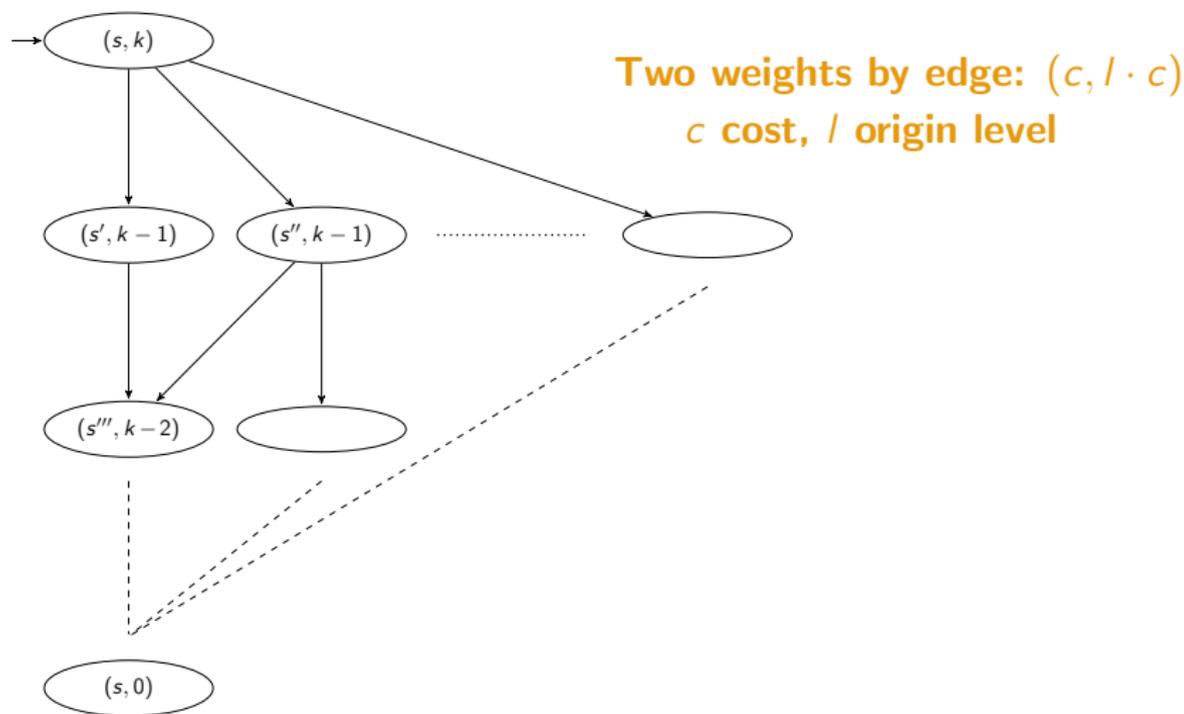
One-player games: P algorithm (2/2)

Computing $\mathcal{C}_{s,k}$: build a **new graph** $\mathcal{G}_{s,k}$ of size $|S| \cdot (k + 1)$.



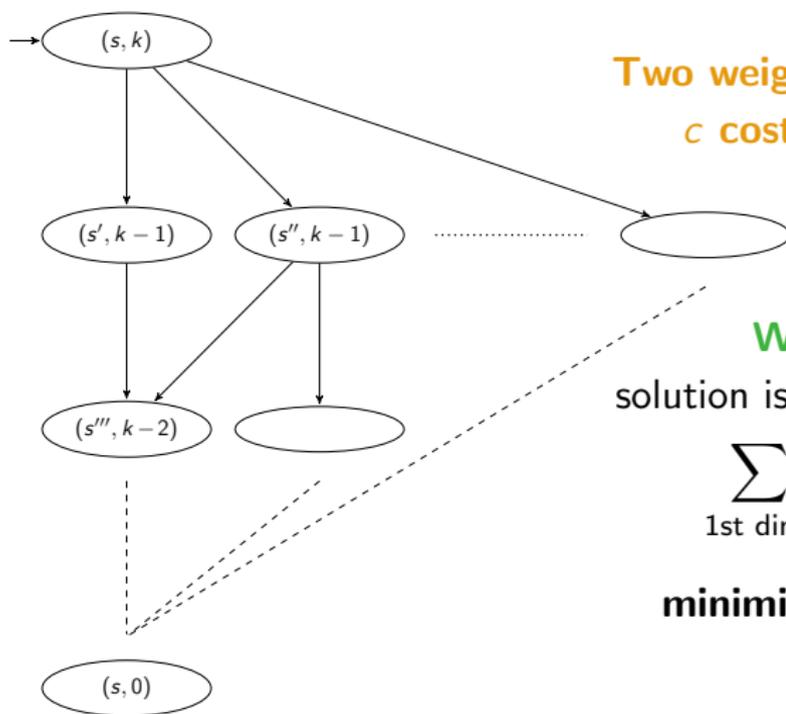
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One-player games: P algorithm (2/2)

Computing $\mathcal{C}_{s,k}$: build a **new graph** $\mathcal{G}_{s,k}$ of size $|S| \cdot (k + 1)$.



Two weights by edge: $(c, l \cdot c)$
 c cost, l origin level

Write an LP s.t.

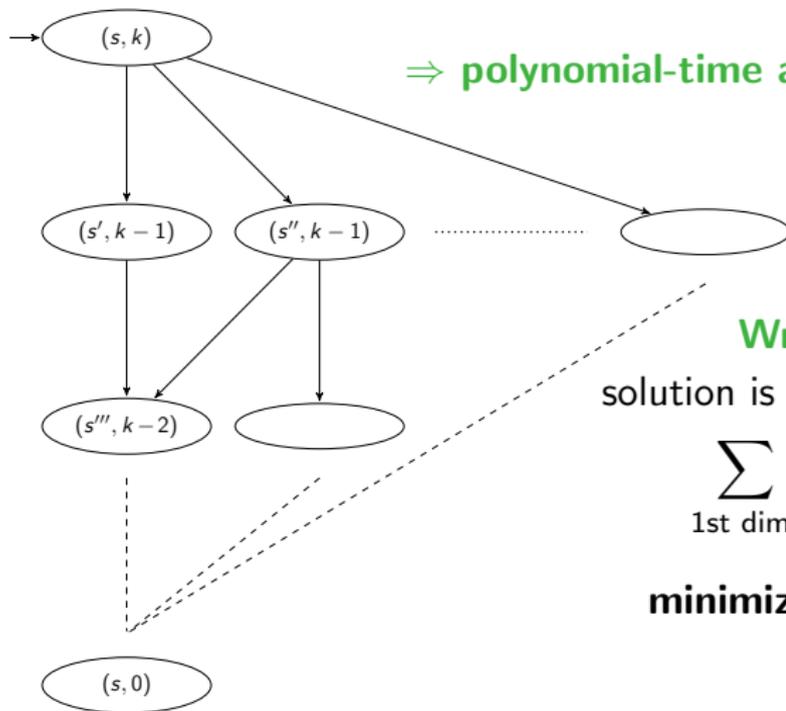
solution is a path from (s, k) to $(s, 0)$

$$\sum_{\text{1st dim.}} = 0 \text{ (zero cycle)}$$

$$\text{minimize } \sum_{\text{2nd dim.}} = AE(C) \cdot k$$

One-player games: P algorithm (2/2)

Computing $C_{s,k}$: build a **new graph** $\mathcal{G}_{s,k}$ of size $|S| \cdot (k + 1)$.



\Rightarrow polynomial-time algorithm for 1-p. games

Write an LP s.t.

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Two-player games

■ Memoryless determinacy

- ▷ Follows from the 1-p. results (minimizer *and* maximizer) using Gimbert and Zielonka [GZ05].

■ Threshold problem in $NP \cap coNP$.

- ▷ Memoryless determinacy + P for one-player games.

■ “Mean-payoff” hard.

- ▷ Replace any edge of weight c by two consecutive edges of values $2 \cdot c$ and $-2 \cdot c$.
- ▷ Use decomposition techniques.
- ▷ $MP(\pi)$ in $G = AE(\pi)$ in G' .

Wrap-up

| Objective | 1-player | 2-player | memory |
|-----------|-------------------------|---|----------------------|
| MP | P [Kar78] | $NP \cap coNP$ [ZP96] | memoryless [EM79] |
| TP | P [FV97] | $NP \cap coNP$ [GS09] | memoryless [GZ04] |
| EG_L | P [BFL ⁺ 08] | $NP \cap coNP$ [CdAHS03, BFL ⁺ 08] | memoryless [CdAHS03] |
| EG_{LU} | PSPACE-c. [FJ13] | EXPTIME-c. [BFL ⁺ 08] | exponential |
| AE | P | $NP \cap coNP$ | memoryless |

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Two settings

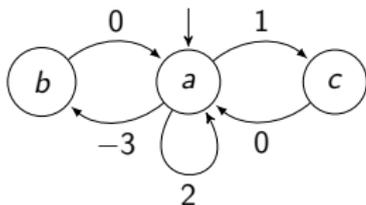
1 AE_{LU} : AE with lower (0) and upper ($U \in \mathbb{N}$) bounds.

2 AE_L : AE with only the lower bound (0).

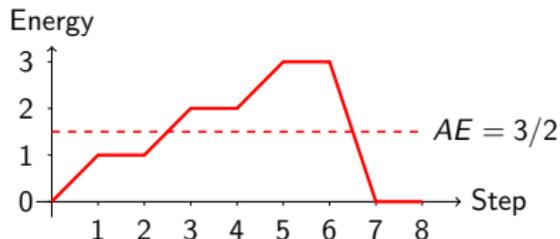
↔ Fixed initial credit $c_{\text{init}} = 0$.

Memory is needed!

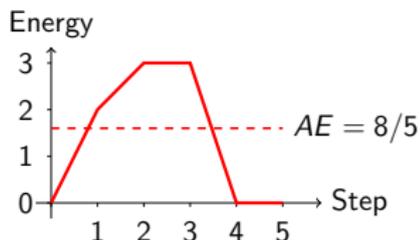
Example: $AE_{LU} \rightsquigarrow$ minimize AE while keeping $EL \in [0, 3]$.



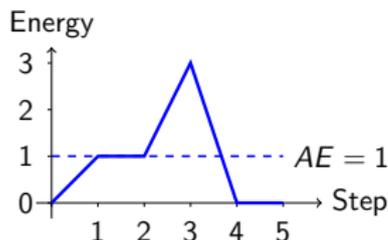
(a) One-player AE_{LU} game.



(b) Play $\pi_1 = (acacacab)^\omega$.



(c) Play $\pi_2 = (aacab)^\omega$.



(d) Play $\pi_3 = (acaab)^\omega$.

Minimal AE with π_3 : alternating between the +1, +2 and -3 cycles.

Memory is needed!

Example: $AE_{LU} \rightsquigarrow$ minimize AE while keeping $EL \in [0, 3]$.

Non-trivial behavior in general!

↔ **Need to choose carefully which cycles to play.**

Memory is needed!

Example: $AE_{LU} \rightsquigarrow$ minimize AE while keeping $EL \in [0, 3]$.

Non-trivial behavior in general!

↪ **Need to choose carefully which cycles to play.**

The AE_{LU} problem is EXPTIME-complete.

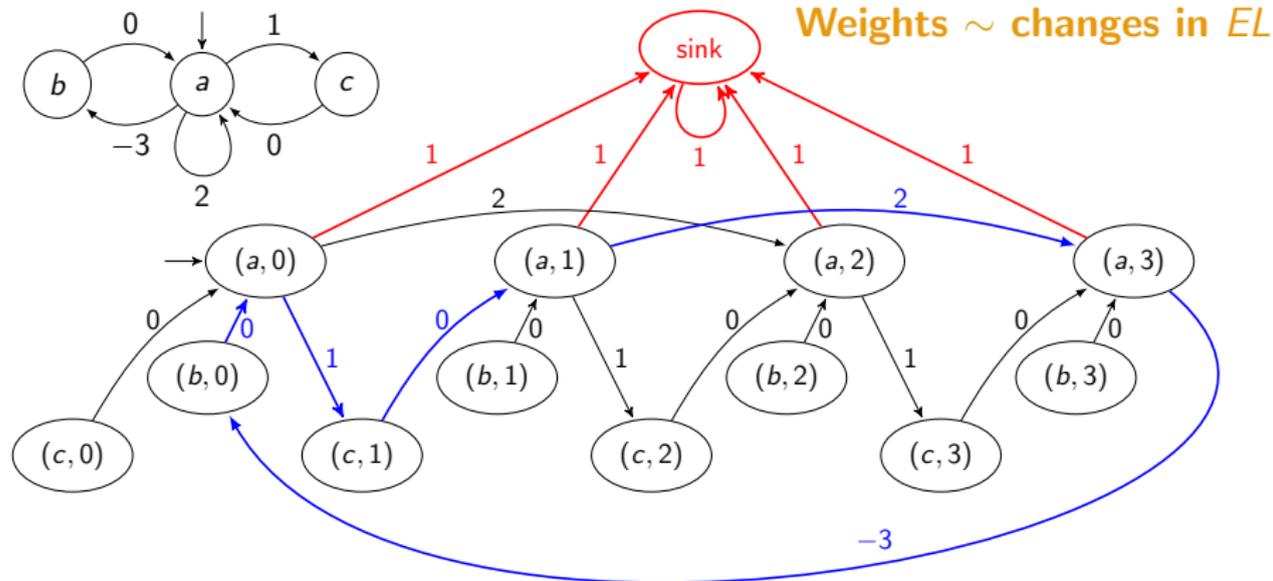
↪ Reduction from AE_{LU} to AE on pseudo-polynomial game
 ($\Rightarrow AE_{LU} \in \text{NEXPTIME} \cap \text{coNEXPTIME}$).

↪ Reduction from this AE game to MP game +
 pseudo-poly. algorithm.

AE_{LU} problem: reduction to AE

↪ Expanded graph constraining the game within the energy bounds $[0, U]$. **Pseudo-polynomial size:** $\mathcal{O}(|S| \cdot (U + 1))$.

↪ If we go out, $AE = \infty$.



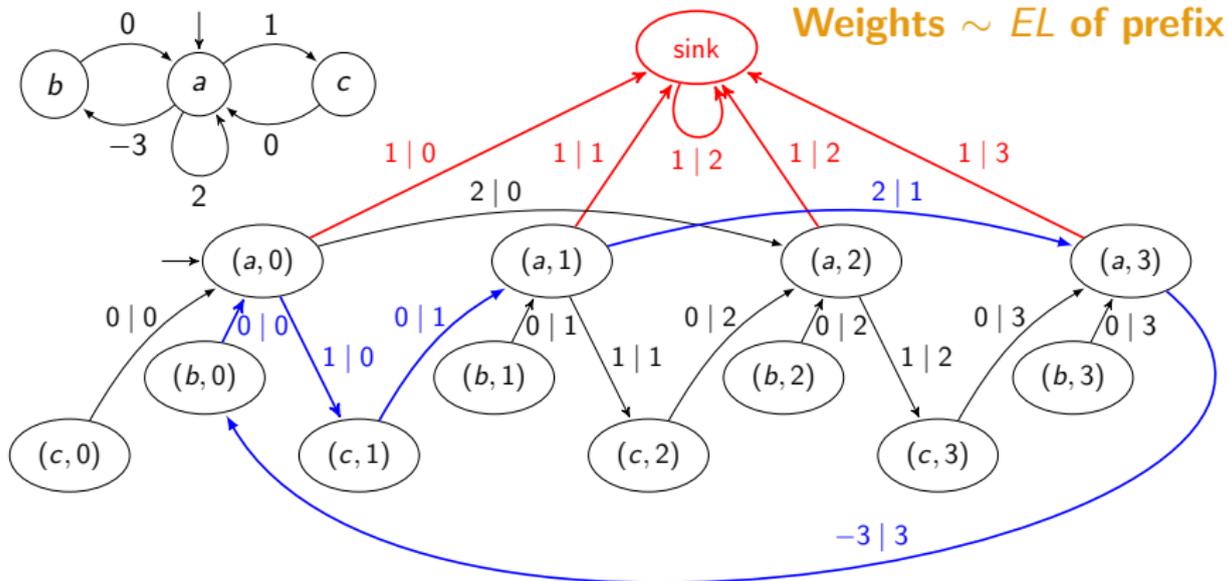
minimal $AE \wedge EL \in [0, 3]$ in $G \iff$ minimal AE in G'

AE_{LU} problem: further reduction to MP

↪ Expanded graph of pseudo-poly. size: $\mathcal{O}(|S| \cdot (U + 1))$.

Threshold for AE : $t = 1$.

↪ If we go out, $MP = \lceil t \rceil + 1 > t \Rightarrow$ losing.



If $\neg(\diamond \text{sink})$: $\overline{AE}(\pi)$ in $G' = \overline{MP}(\pi)$ in G''

AE_{LU} problem: complexity

| Objective | 1-player | 2-player | memory |
|------------------------|-------------------------|---|----------------------|
| MP | P [Kar78] | $NP \cap coNP$ [ZP96] | memoryless [EM79] |
| TP | P [FV97] | $NP \cap coNP$ [GS09] | memoryless [GZ04] |
| EG_L | P [BFL ⁺ 08] | $NP \cap coNP$ [CdAHS03, BFL ⁺ 08] | memoryless [CdAHS03] |
| EG_{LU} | PSPACE-c. [FJ13] | EXPTIME-c. [BFL ⁺ 08] | exponential |
| AE | P | $NP \cap coNP$ | memoryless |
| AE_{LU} (poly. U) | P | $NP \cap coNP$ | polynomial |
| AE_{LU} (arbitrary) | EXPTIME-e./PSPACE-h. | EXPTIME-c. | exponential |

- ▷ Pseudo-poly. algo. to solve the MP problem (e.g., [BCD⁺11]).
- ▷ Lower bounds follow from EG_{LU} .
- ▷ Exponential memory is both necessary and sufficient.

AE_L problem: partial answers

■ One-player games.

- ↪ **Key argument:** upper-bounding the value of the energy over a witness winning path.
- ↪ Pseudo-polynomial bound for U , then **reduction to an AE_{LU} problem.**
- ↪ EXPTIME-algorithm.
- ↪ **Lower bound:** NP-hard via *subset sum problem* [GJ79].

AE_L problem: partial answers

■ One-player games.

- ↪ **Key argument:** upper-bounding the value of the energy over a witness winning path.
- ↪ Pseudo-polynomial bound for U , then **reduction to an AE_{LU} problem.**
- ↪ EXPTIME-algorithm.
- ↪ **Lower bound:** NP-hard via *subset sum problem* [GJ79].

■ Two-player games.

- ↪ Decidability is open.
- ↪ **Lower bound:** EXPTIME-hard via *countdown games* [JSL08].

AE_L problem: complexity

| Objective | 1-player | 2-player | memory |
|------------------------|-------------------------|---|----------------------|
| MP | P [Kar78] | $NP \cap coNP$ [ZP96] | memoryless [EM79] |
| TP | P [FV97] | $NP \cap coNP$ [GS09] | memoryless [GZ04] |
| EG_L | P [BFL ⁺ 08] | $NP \cap coNP$ [CdAHS03, BFL ⁺ 08] | memoryless [CdAHS03] |
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| AE_{LU} (poly. U) | P | $NP \cap coNP$ | polynomial |
| AE_{LU} (arbitrary) | EXPTIME-e./PSPACE-h. | EXPTIME-c. | exponential |
| AE_L | EXPTIME-e./NP-h. | open/EXPTIME-h. | open (required) |

- 1 Context & Definitions
- 2 Average-Energy Games
- 3 Average-Energy with Energy Constraints
- 4 Conclusion**

Wrap-up

“New” quantitative objective.

- ▷ Practical motivations (e.g., HYDAC).
- ▷ “Refines” TP (and MP).
- ▷ Same complexity class as EG_L , MP and TP games.
- ▷ AE_{LU} well-understood.
- ▷ Open questions for AE_L .
 - ↪ Mostly theoretical interest (unbounded energy capacity is not realistic).

Thank you! Any question?

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